



A14.1 The systems lifecycle and feasibility

Software development, law and ethics · A level · OCR H446 1.2.3, AQA
7517 4.13.1.1, Eduqas A500QS 1.5 · about 35 min

What this lesson is about

The stages from feasibility to maintenance, the three kinds of maintenance, and scoring a feasibility study.

- Systems analysis
- The stages
- The feasibility study
- Fact finding
- Installation and changeover
- Maintenance
- Evaluation

Questions

6 marks in all

1. Put these stages of the systems lifecycle in order.

[1 mark]

Number the lines 1 to 6 to put them in the right order.

- ___ Feasibility study
- ___ Testing
- ___ Analysis
- ___ Implementation
- ___ Evaluation
- ___ Design

Answer:

Feasibility study
Analysis
Design
Implementation
Testing
Evaluation

Each stage uses what the one before produced: the requirements from analysis are designed, built, tested and finally evaluated.

2. What is the purpose of a feasibility study?

[1 mark]

- ☐ A To decide whether the project is possible and worth doing before money is spent on it
- ☐ B To find and fix the errors in the finished program
- ☐ C To write the program's user documentation
- ☐ D To train the users on the new system

Answer: A. A feasibility study weighs technical, economic, legal, operational and schedule factors and recommends whether to go ahead.

3. A school opens a new wing, so the delivery robot's software is changed to include the new corridors. [1 mark]
What kind of maintenance is this?

- ☐ A Adaptive
☐ B Corrective
☐ C Perfective
☐ D Destructive

Answer: A. Adaptive maintenance changes a system because its environment has changed; corrective fixes errors and perfective improves it.

4. Which of these are aspects considered in a feasibility study? [1 mark]

Tick every answer that is true.

- ☐ A Legal
☐ B Economic
☐ C Schedule
☐ D Syntax
☐ E Pair programming

Answer: A, B, C. TELOS: technical, economic, legal, operational and schedule. Syntax and pair programming belong to implementation.

5. Against what should a finished system be evaluated? [1 mark]

- ☐ A The success criteria agreed during analysis
☐ B How much code was written
☐ C Whether the developers enjoyed building it
☐ D The number of tests that were run

Answer: A. Evaluation checks each agreed criterion with evidence, and considers qualities such as usability and maintainability.

6. A feasibility study scores each aspect and weights it. What does this print? [1 mark]

```
aspects = [("technical", 4, 3), ("economic", 2, 2), ("legal", 5, 1)]
total = sum(s * w for _, s, w in aspects)
weights = sum(w for _, _, w in aspects)
print(total, weights, round(total / weights, 1))
```

Answer:

21 6 3.5

The total is $12 + 4 + 5 = 21$ over weights $3 + 2 + 1 = 6$, giving 3.5.

The task: the feasibility study

Four robot projects have been scored for feasibility. `proposals` is a list of `(name, aspects)`, where `name` is a string and `aspects` is a list of five tuples `(aspect, score, weight)`: `aspect` is a string, `score` is a whole number from 0 to 5, and `weight` is a whole number from 1 to 3. Write two functions: - `weighted_score(aspects)` returns the total of `score * weight` divided by the total of the weights, rounded to one decimal place. - `blockers(aspects)` returns a list of the names of the aspects that score less than 2, in the order they appear. Then, for each proposal in order, print one line: `<name>: <score> <verdict>`, with the score to one decimal place. The verdict is `not feasible (blocked by <aspects>)` if there are any blockers, with their names separated by `,` ; otherwise `not feasible (score below 3)` if the score is less than 3; otherwise `feasible`. For example, `delivery robot: 3.5 feasible`. The robot stays still.

```
# the two lines every program starts with: the commands, then the robot
from bugbot import *
connect()

proposals = [
    ("delivery robot", [("technical", 4, 3), ("economic", 3, 2), ("legal", 4, 2),
    ("operational", 3, 2), ("schedule", 3, 1)]),
    ("face-recognition door", [("technical", 4, 3), ("economic", 4, 2), ("legal", 1, 2),
    ("operational", 3, 2), ("schedule", 4, 1)]),
    ("robot lawnmower fleet", [("technical", 3, 3), ("economic", 2, 2), ("legal", 3, 2),
    ("operational", 3, 2), ("schedule", 2, 1)]),
    ("voice-controlled lift", [("technical", 1, 3), ("economic", 1, 2), ("legal", 4, 2),
    ("operational", 3, 2), ("schedule", 4, 1)]),
]

def weighted_score(aspects):
    pass

def blockers(aspects):
    pass
```

The hint students can ask for: The weighted score is the total of score times weight, divided by the total of the weights. Find the blockers first, because a proposal with a blocker fails whatever its score; only then compare the score with 3.

A solution

```
# the two lines every program starts with: the commands, then the robot
from bugbot import *
connect()

proposals = [
    ("delivery robot", [("technical", 4, 3), ("economic", 3, 2), ("legal", 4, 2),
    ("operational", 3, 2), ("schedule", 3, 1)]),
    ("face-recognition door", [("technical", 4, 3), ("economic", 4, 2), ("legal", 1, 2),
    ("operational", 3, 2), ("schedule", 4, 1)]),
    ("robot lawnmower fleet", [("technical", 3, 3), ("economic", 2, 2), ("legal", 3, 2),
    ("operational", 3, 2), ("schedule", 2, 1)]),
    ("voice-controlled lift", [("technical", 1, 3), ("economic", 1, 2), ("legal", 4, 2),
    ("operational", 3, 2), ("schedule", 4, 1)]),
]

def weighted_score(aspects):
    total = sum(score * weight for _, score, weight in aspects)
```

```

weights = sum(weight for _, _, weight in aspects)
return round(total / weights, 1)

def blockers(aspects):
    return [name for name, score, _ in aspects if score < 2]

for name, aspects in proposals:
    score = weighted_score(aspects)
    blocked = blockers(aspects)
    if blocked:
        verdict = "not feasible (blocked by " + ", ".join(blocked) + ")"
    elif score < 3:
        verdict = "not feasible (score below 3)"
    else:
        verdict = "feasible"
    print(f"{name}: {score:.1f} {verdict}")

```

Any program that meets the task's checks is marked correct in the simulator; this is one way, not the only way.