



A14.1 The systems lifecycle and feasibility

Software development, law and ethics · A level · OCR H446 1.2.3, AQA
7517 4.13.1.1, Eduqas A500QS 1.5 · about 35 min

Name _____

Class _____

Date _____

What this lesson is about

The stages from feasibility to maintenance, the three kinds of maintenance, and scoring a feasibility study.

- Systems analysis
- The stages
- The feasibility study
- Fact finding
- Installation and changeover
- Maintenance
- Evaluation

Questions

6 marks in all

1. Put these stages of the systems lifecycle in order.

[1 mark]

Number the lines 1 to 6 to put them in the right order.

- ___ Feasibility study
- ___ Testing
- ___ Analysis
- ___ Implementation
- ___ Evaluation
- ___ Design

2. What is the purpose of a feasibility study?

[1 mark]

- ☐ A To decide whether the project is possible and worth doing before money is spent on it
- ☐ B To find and fix the errors in the finished program
- ☐ C To write the program's user documentation
- ☐ D To train the users on the new system

3. A school opens a new wing, so the delivery robot's software is changed to include the new corridors.

[1 mark]

What kind of maintenance is this?

- ☐ A Adaptive
- ☐ B Corrective
- ☐ C Perfective
- ☐ D Destructive

4. Which of these are aspects considered in a feasibility study?

[1 mark]

Tick every answer that is true.

- ☐ A Legal
- ☐ B Economic
- ☐ C Schedule
- ☐ D Syntax
- ☐ E Pair programming

5. Against what should a finished system be evaluated?

[1 mark]

- ☐ A The success criteria agreed during analysis
- ☐ B How much code was written
- ☐ C Whether the developers enjoyed building it
- ☐ D The number of tests that were run

6. A feasibility study scores each aspect and weights it. What does this print?

[1 mark]

```
aspects = [("technical", 4, 3), ("economic", 2, 2), ("legal", 5, 1)]
total = sum(s * w for _, s, w in aspects)
weights = sum(w for _, _, w in aspects)
print(total, weights, round(total / weights, 1))
```

The task: the feasibility study

Four robot projects have been scored for feasibility. `proposals` is a list of `(name, aspects)`, where `name` is a string and `aspects` is a list of five tuples `(aspect, score, weight)`: `aspect` is a string, `score` is a whole number from 0 to 5, and `weight` is a whole number from 1 to 3. Write two functions: - `weighted_score(aspects)` returns the total of `score * weight` divided by the total of the weights, rounded to one decimal place. - `blockers(aspects)` returns a list of the names of the aspects that score less than 2, in the order they appear. Then, for each proposal in order, print one line: `<name>: <score> <verdict>`, with the score to one decimal place. The verdict is `not feasible (blocked by <aspects>)` if there are any blockers, with their names separated by `,` ; otherwise `not feasible (score below 3)` if the score is less than 3; otherwise `feasible`. For example, `delivery robot: 3.5 feasible`. The robot stays still.

```
# the two lines every program starts with: the commands, then the robot
from bugbot import *
connect()

proposals = [
    ("delivery robot", [("technical", 4, 3), ("economic", 3, 2), ("legal", 4, 2),
    ("operational", 3, 2), ("schedule", 3, 1)]),
    ("face-recognition door", [("technical", 4, 3), ("economic", 4, 2), ("legal", 1, 2),
    ("operational", 3, 2), ("schedule", 4, 1)]),
    ("robot lawnmower fleet", [("technical", 3, 3), ("economic", 2, 2), ("legal", 3, 2),
    ("operational", 3, 2), ("schedule", 2, 1)]),
    ("voice-controlled lift", [("technical", 1, 3), ("economic", 1, 2), ("legal", 4, 2),
    ("operational", 3, 2), ("schedule", 4, 1)]),
]

def weighted_score(aspects):
    pass

def blockers(aspects):
    pass
```

Plan your program here, then type it in and press Run.



Do it on the robot

www.bugbotlab.com/learn/a14-1-the-systems-lifecycle/

The simulator checks it and tells you when it passes. Nothing to install, no account.

Challenges

1. The face-recognition door scores well overall but is blocked on legal grounds. Write two sentences explaining why a legal problem should stop a project that scores 3.2.

2. Classify each change as corrective, adaptive or perfective: the robot is updated for a new floor plan; a crash when the battery reads 0 is fixed; the route planner is made faster.
3. Suggest the changeover method you would use for the delivery robot, and justify it in terms of the risk to the school.